

Suboptimal and Anytime Heuristic Search on Multi-core Machines

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Overview

Introduction

■ Overview

■ Parallel Search

PRA*

PBNF

Optimal Search

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Conclusion

- Background
 - ◆ Parallel Retracting A* (PRA*, Evett et al., 1995)
 - ◆ Parallel Best N Block First Search (PBNF, Burns et al., IJCAI 2009)
- New: Parallel bounded-suboptimal search.
 - ◆ Two pruning rules for approximate best-first suboptimal search
- New: Parallel anytime search.

Naive Parallel Search

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PRA*

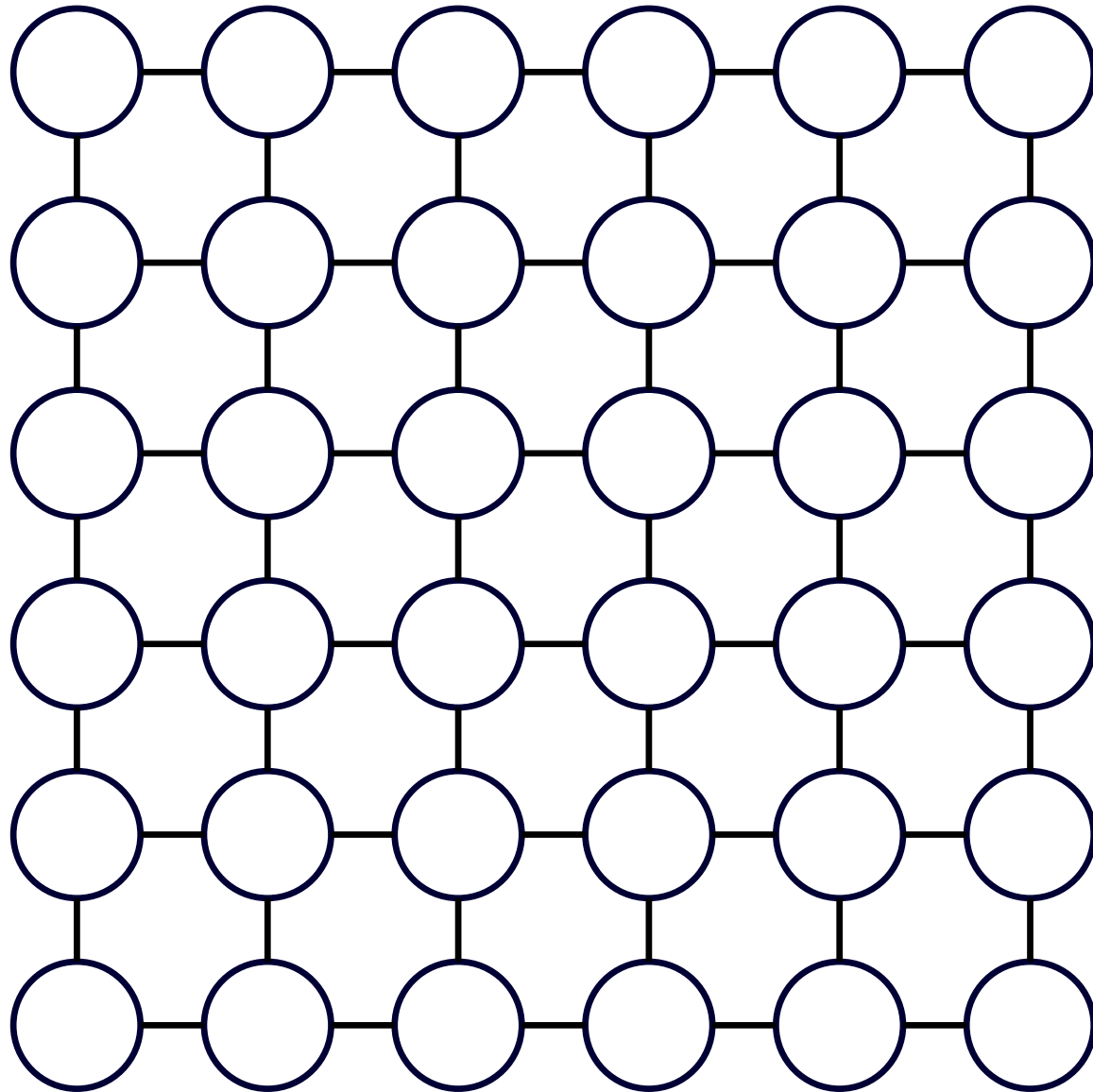
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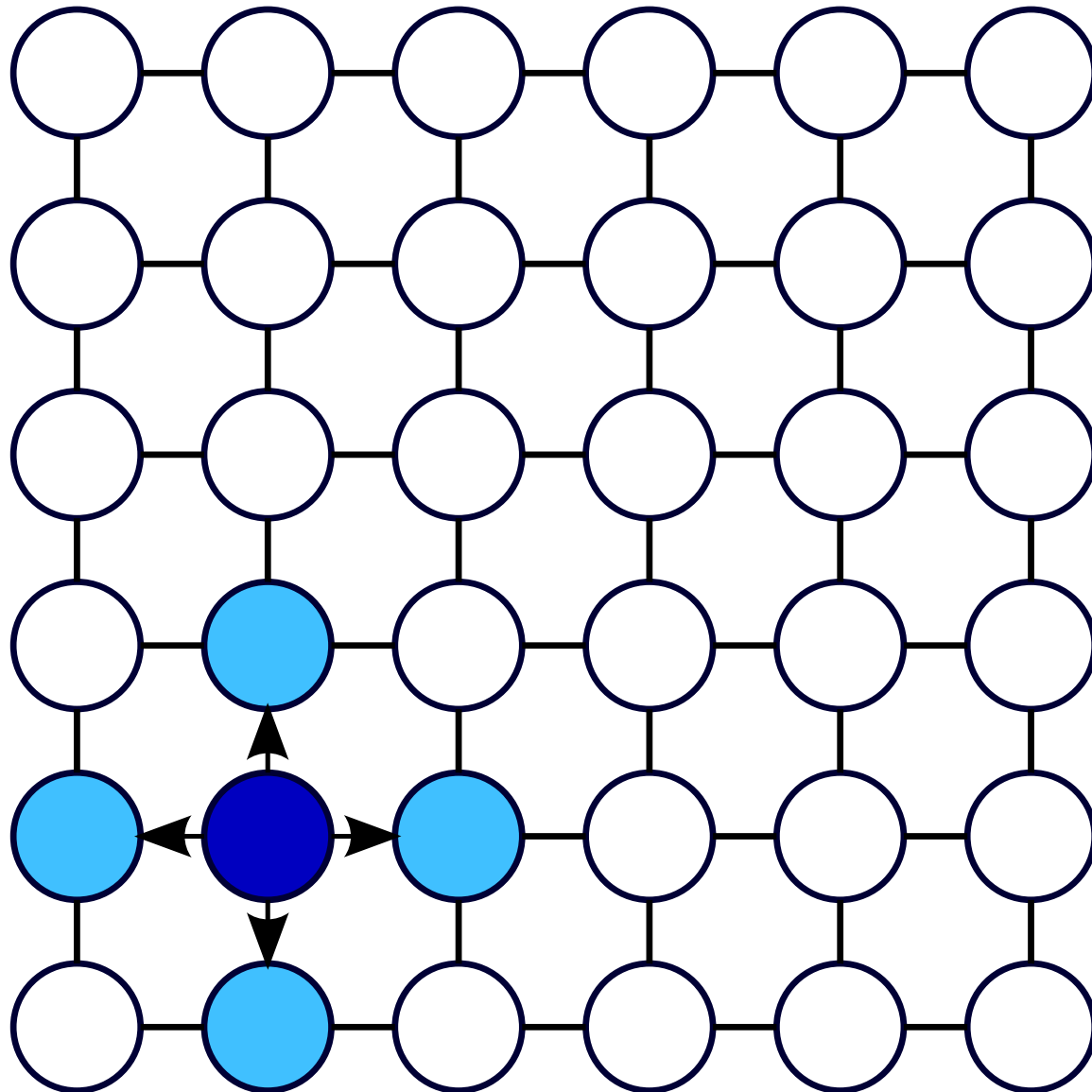
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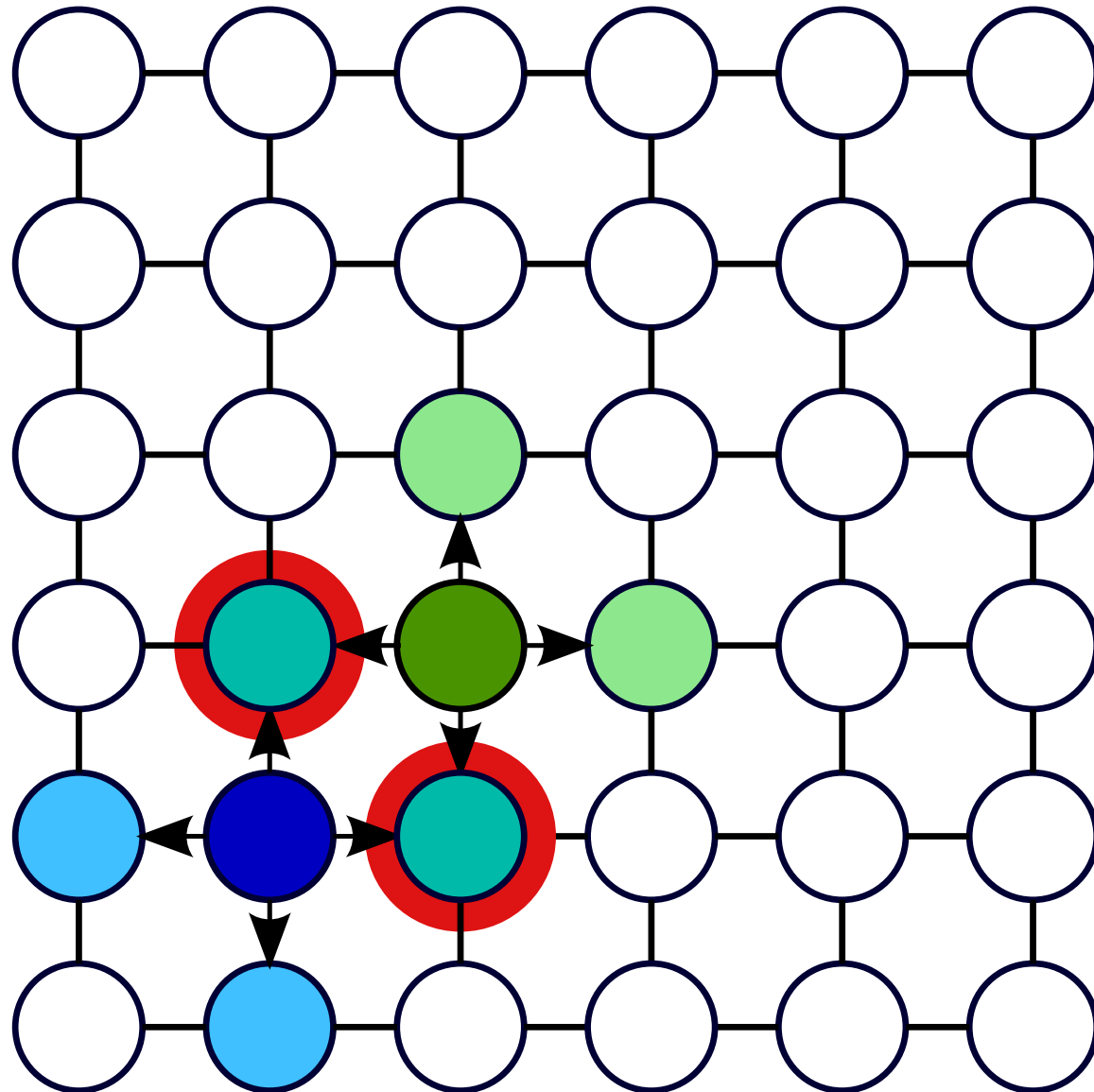
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Parallel Retracting A* (PRA*, Evett et al., 1995)

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PRA*

■ Hashing Nodes

■ Communication

PBNF

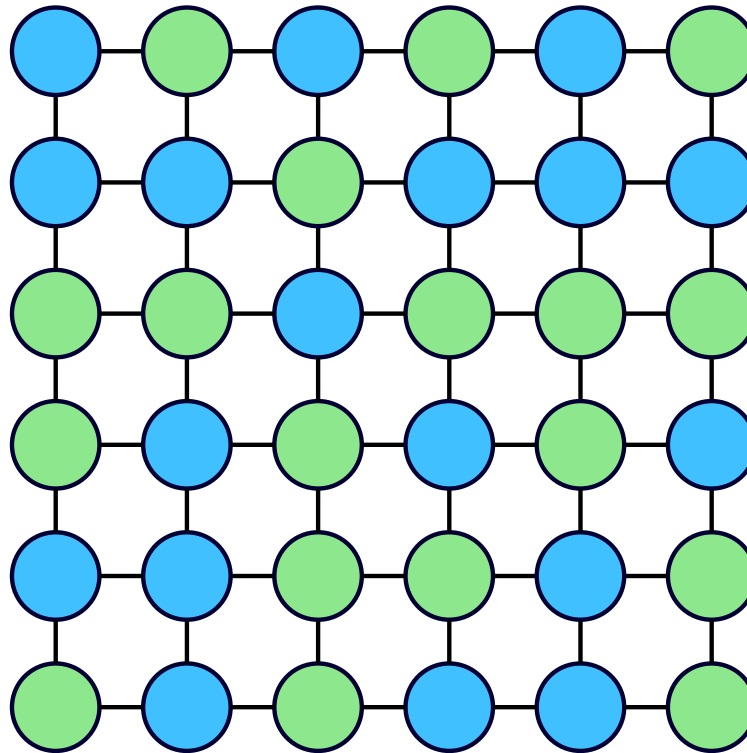
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- Distribute nodes among threads using a hash function.
 - ◆ Each node has a home thread.
 - ◆ Duplicate detection can be performed locally at each thread.



Parallel Retracting A* (PRA*, Evett et al., 1995)

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PRA*

■ Hashing Nodes

■ Communication

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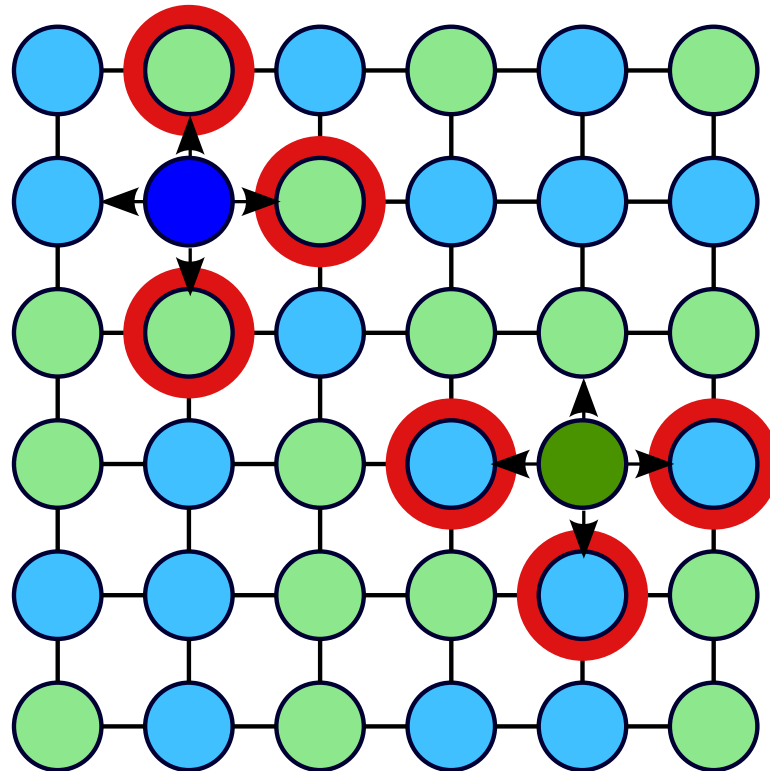
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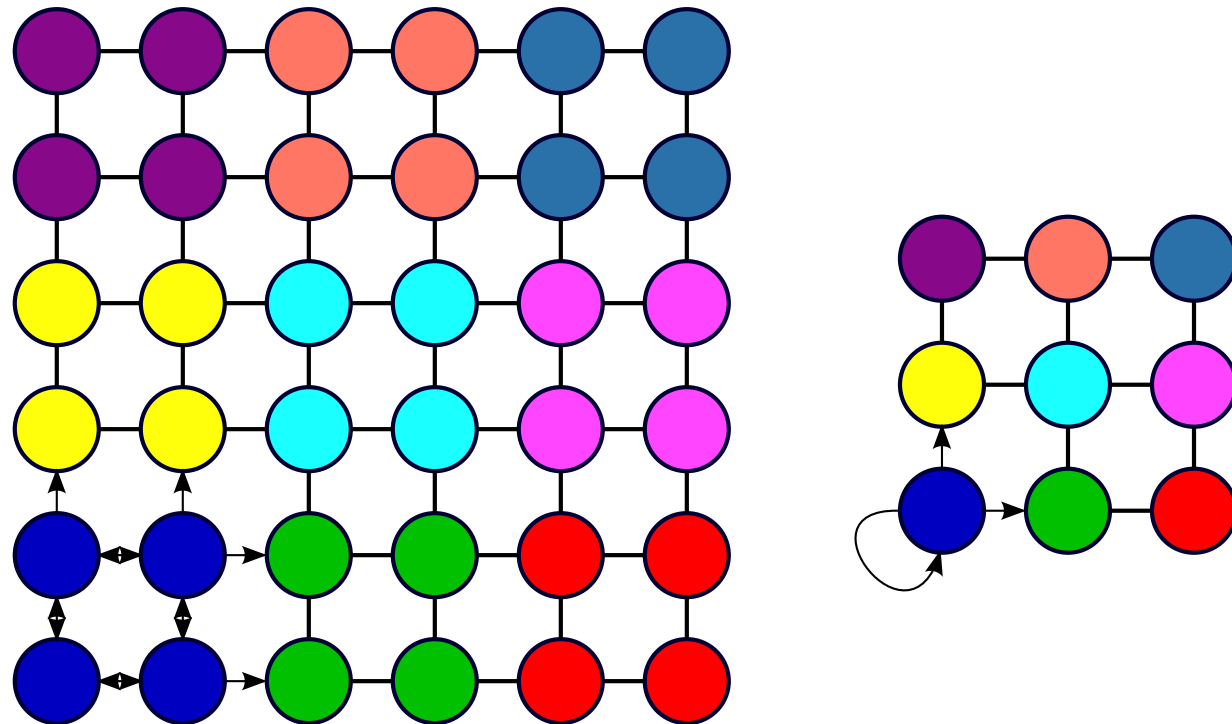
Conclusion

- May need to communicate nodes between threads at each generation.
- Non-blocking: HDA* (Kishimoto et al., best paper award ICAPS 2009)



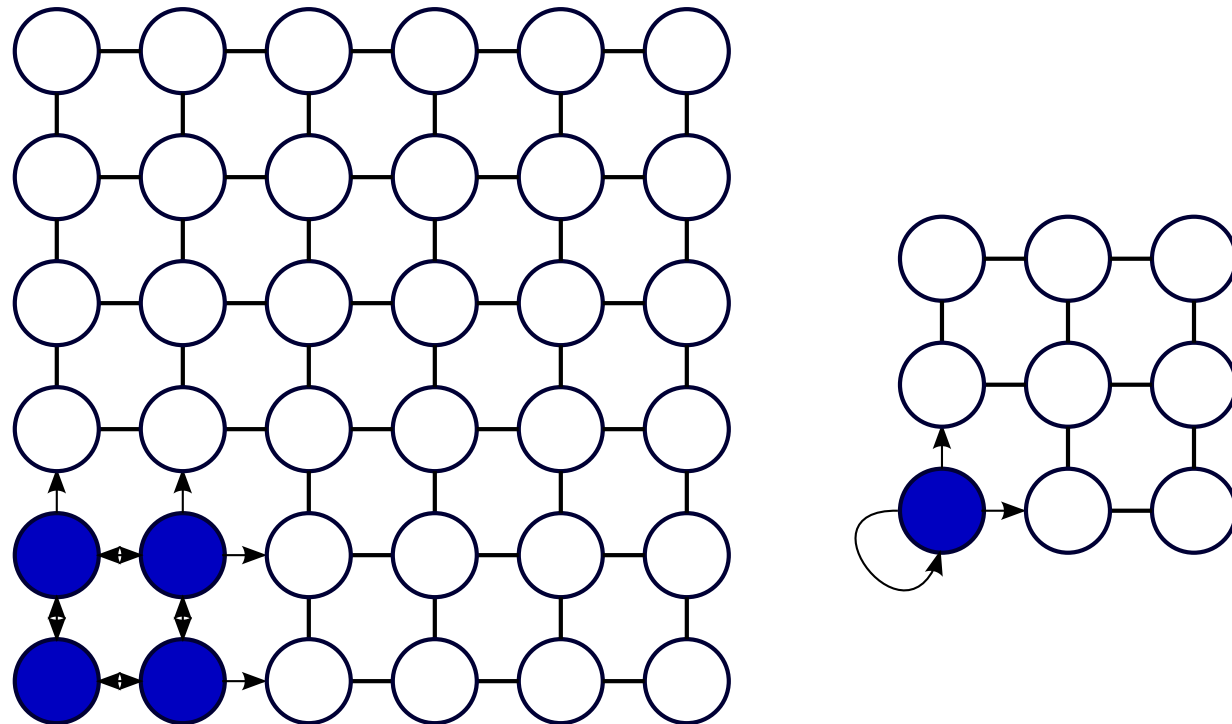
Parallel Best N block First (PBNF, Burns et al., 2009)

- Work is divided among threads using a special hash function based on abstraction. (Zhou and Hansen, 2007)
- ◆ Few possible destinations for children.



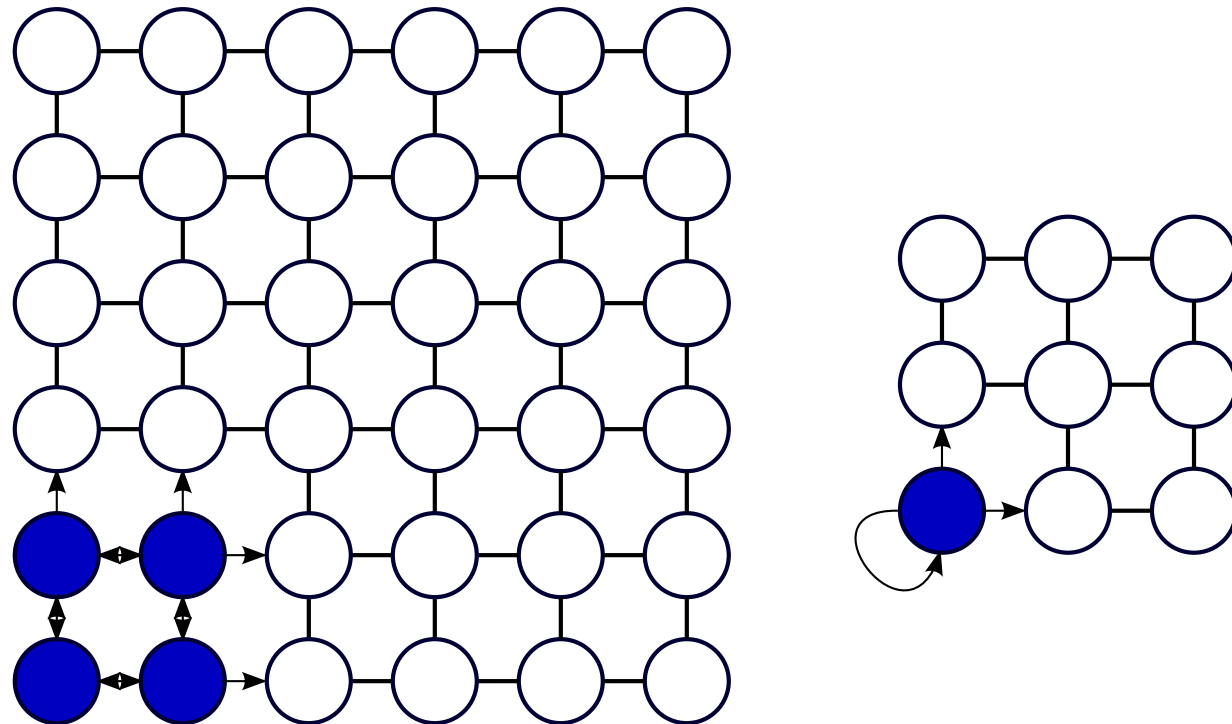
Parallel Best N block First (PBNF, Burns et al., IJCAI 2009)

- Work is divided among threads using a special hash function based on abstraction.
- ◆ Threads search groups of nodes called n blocks.



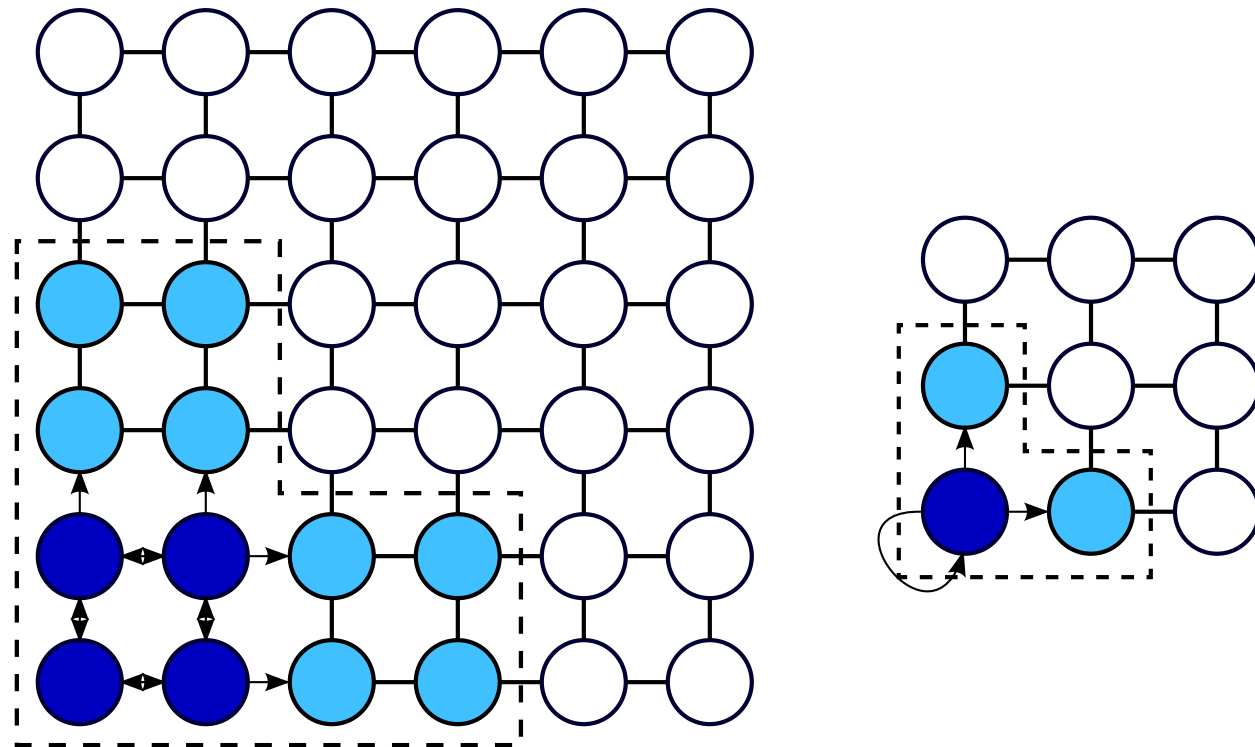
Parallel Best N block First (PBNF, Burns et al., IJCAI 2009)

- Work is divided among threads using a special hash function based on abstraction.
- ◆ n blocks have an open and closed list.



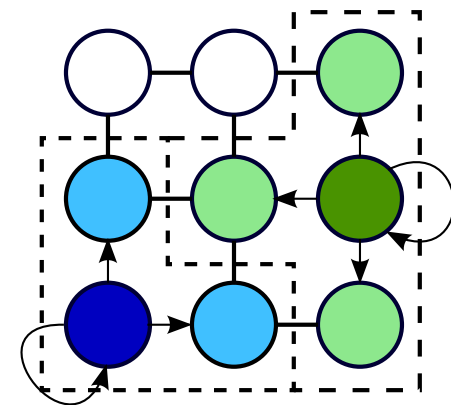
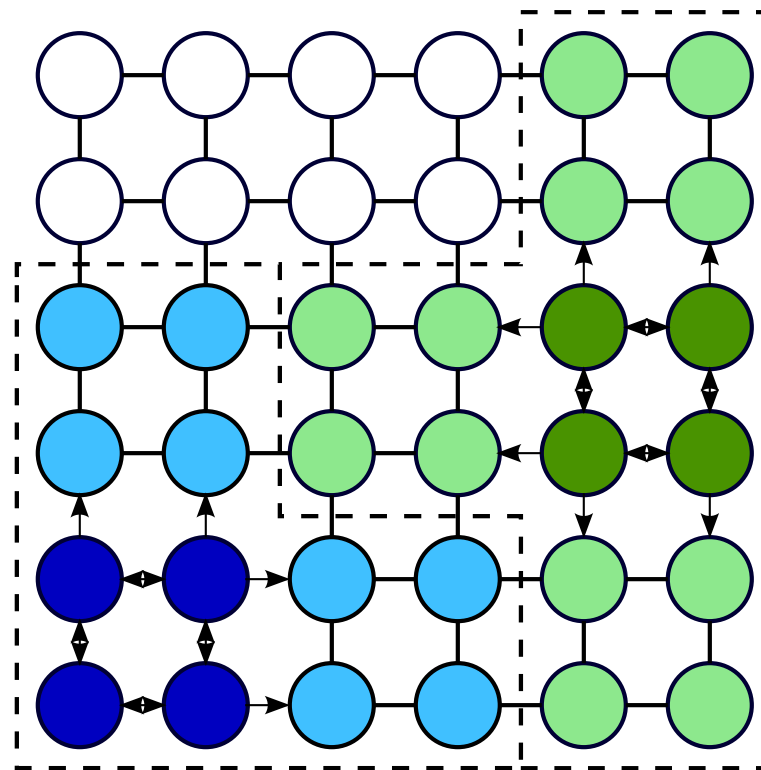
Parallel Best N block First (PBNF, Burns et al., IJCAI 2009)

- Work is divided among threads using a special hash function based on abstraction.
- ◆ An n block and its successors: *duplicate detection scope*.



Parallel Best N block First (PBNF, Burns et al., IJCAI 2009)

- Work is divided among threads using a special hash function based on abstraction.
- ◆ *Disjoint* duplicate detection scopes searched in parallel.



Parallel Best N Block First (PBNF, Burns et al., IJCAI 2009)

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■ Abstraction

■ N blocks

■ Detection Scope

■ Disjoint Scopes

■ PBNF

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1. Search disjoint n blocks in parallel.
 - Maintain a heap of free n blocks.
 - **Greedily** acquire best free n block (and its scope).
2. Each n block is searched in $f(n) = g(n) + h(n)$ order.
 - Switch n blocks when a better one becomes free.
 - **Approximates** best-first order.
3. Stop when the incumbent solution is optimal.
 - Prune nodes on the cost of the incumbent
 - Incumbent is optimal when all nodes are pruned.
4. See paper for proof of correctness (no livelock).

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Optimal Search (New since paper)

Algorithms Not Shown

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Parallel A*

- Basic A* with a lock on open and closed lists.

Lock-free PA*

- PA* with lock-free data structures.

KBFS (Felner et al., 2003)

- Expand the K best open nodes in parallel.

PSDD (Zhou and Hansen, 2007)

- Abstraction to find disjoint portions of a search space.
- Breadth-first search
- All threads synchronize at each layer

IDPSDD

- PSDD with iterative-deepening for bounds.

BFPSDD*

- PSDD, but search in $f(n)$ layers.

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PRA* (Evetts et al., 1995)

- Distributes nodes with a hash function.

HDA* (Kishimoto et al., ICAPS 2009)

- PRA* with non-blocking communication.
- Originally developed for distributed memory.

APRA* and AHDA*

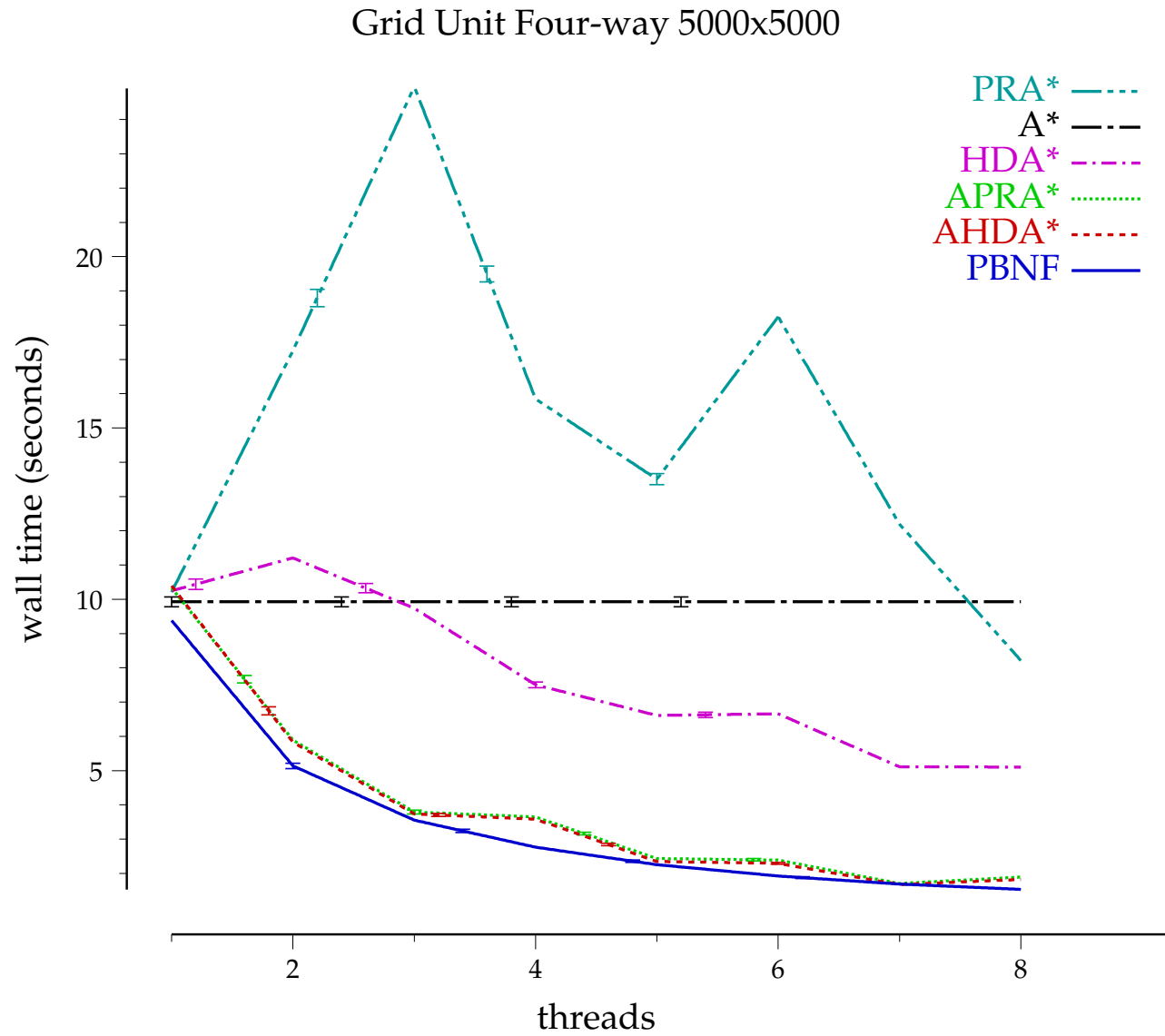
- PRA* and HDA* with abstraction based hashing function.

PBNF (Burns et al., IJCAI 2009)

- Uses abstraction to decompose the search space.
- Greedily acquire best free nodes.

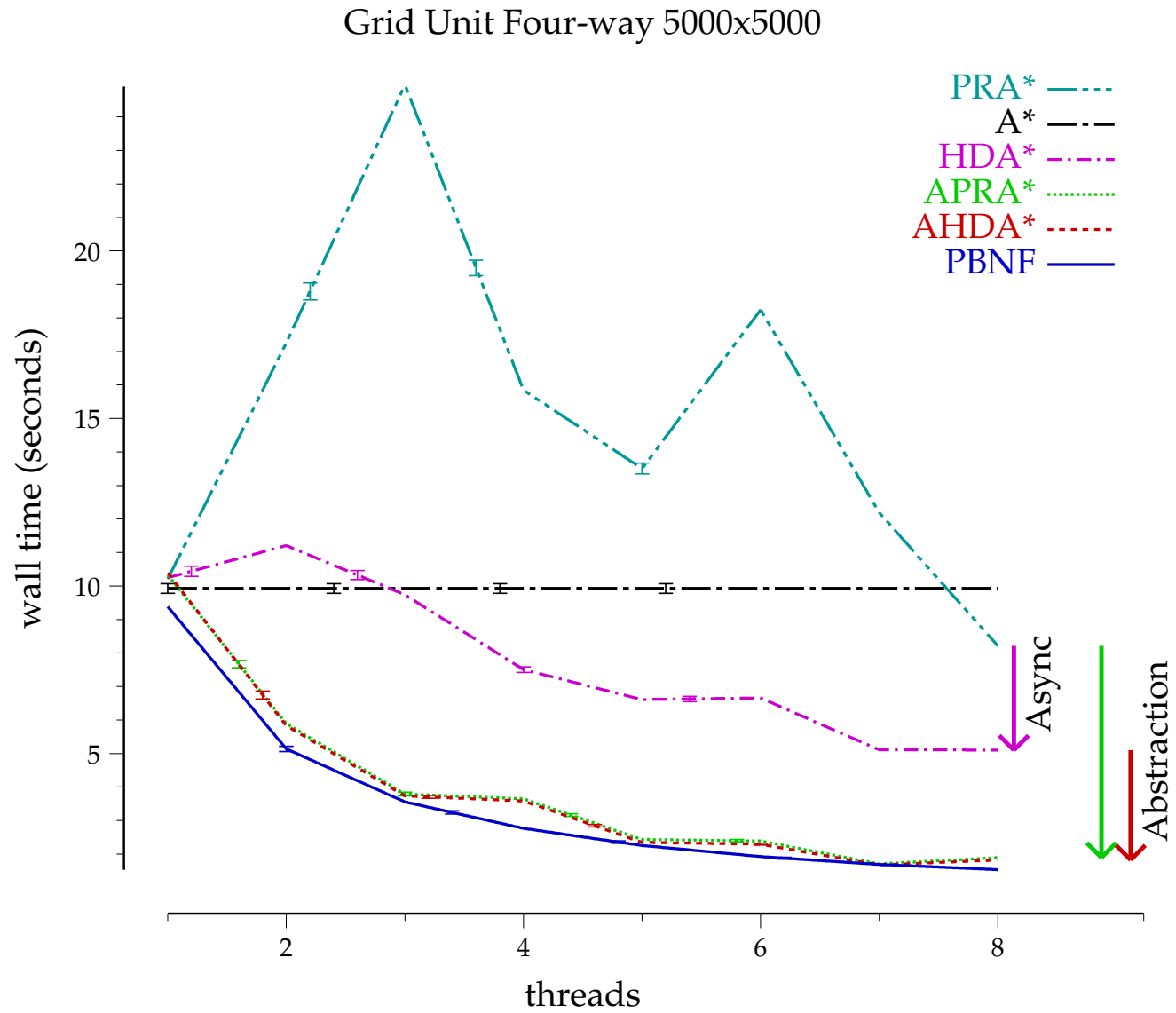
Four-way Grid Pathfinding 5000x5000

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Easy 15-Puzzles

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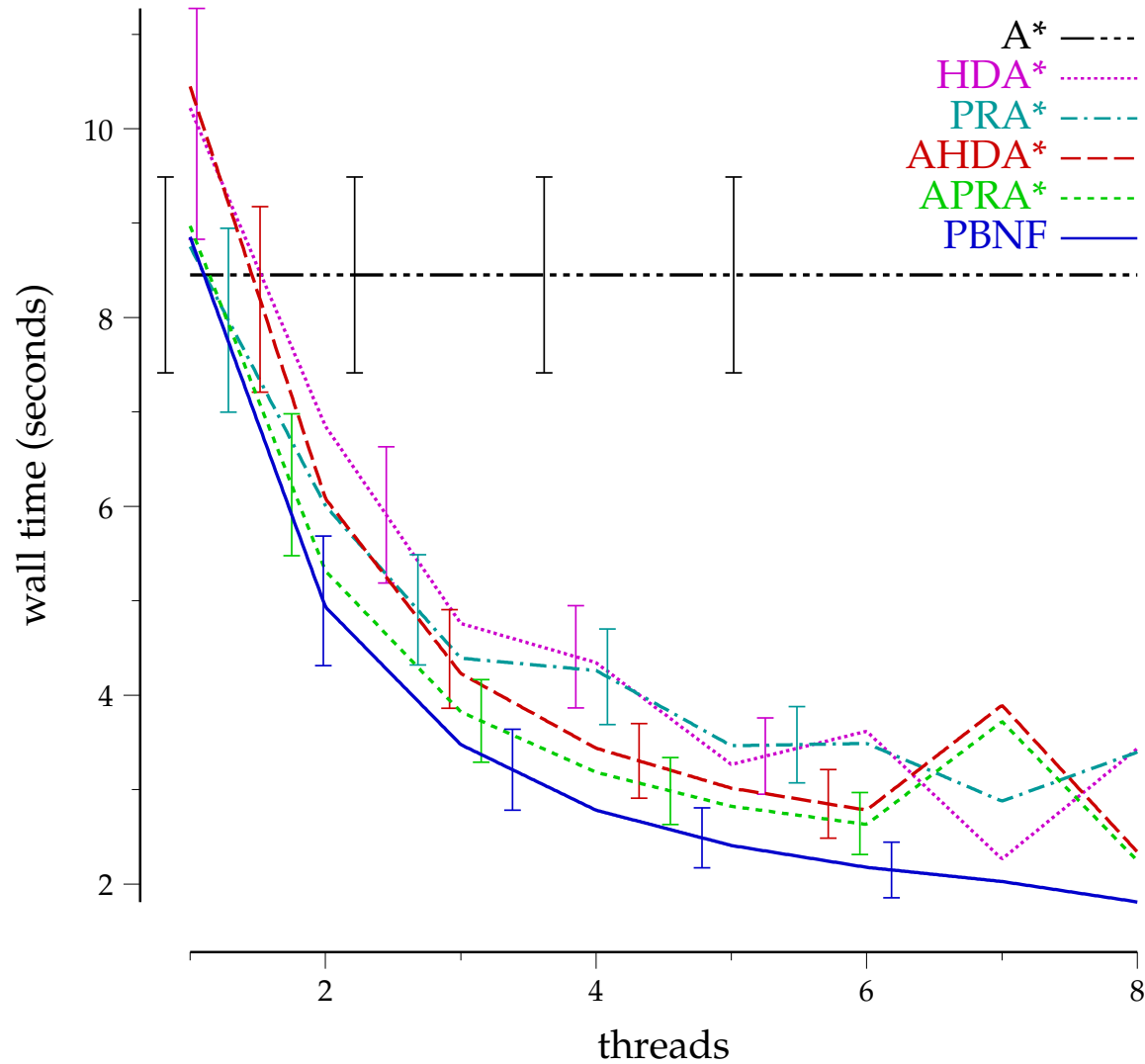
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15 puzzles: 250 random easy instances



Optimal STRIPS Planning

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	threads	logistics-6	blocks-14	gripper-7	satellite-6	elevator-12	freecell-3	depots-7	driverlog-11	gripper-8
A*	1	2.30	5.19	117.78	130.85	335.74	199.06	M	M	M
APRA*	1	1.44	7.37	62.61	95.11	215.19	153.71	319.48	334.28	569.26
	3	0.75	5.30	43.13	42.85	243.24	122.00	138.30	99.37	351.87
	5	1.09	3.26	37.62	67.38	211.45	63.47	67.24	89.73	236.93
	7	0.81	2.92	26.78	52.82	169.92	37.94	49.58	104.87	166.19
AHDA*	1	1.44	7.13	59.51	95.50	206.16	147.96	299.66	315.51	532.51
	3	0.70	5.07	33.95	33.59	96.82	93.55	126.34	85.17	239.22
	5	0.48	2.25	15.97	24.11	67.68	38.24	50.97	51.28	97.61
	7	0.40	2.13	12.69	18.24	57.10	27.37	39.10	48.91	76.34
PBNF	1	1.17	6.21	39.58	77.02	150.39	127.07	156.36	154.15	235.46
	3	0.64	2.69	16.87	24.09	53.45	47.10	63.04	59.98	98.21
	5	0.56	2.20	11.23	17.29	34.23	38.07	42.91	38.84	63.65
	7	0.62	2.02	9.21	13.67	27.02	37.02	34.66	31.22	51.50

Wall time in seconds

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- PBNF gave the best performance and scalability across all domains tested.
- Non-blocking communication improved the performance of PRA*, confirming results from (Kishimoto et al., 2009).
- Abstraction improved the performance of PRA* and HDA*.

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Bounded Suboptimal Search

Bounded suboptimal

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- Simple to convert PRA* and PBNF to bounded suboptimal
 - ◆ Sort open lists on $f'(n) = g(n) + w \cdot h(n)$.
 - ◆ Stop when $\min_{n \in open} w \cdot f(n) \geq g(s)$.
 - ◆ Two new pruning rules: see paper.
- Suboptimal PBNF
 - ◆ Sort *n*block free-list on $\min_{n \in open} f'(n)$.

Four-way Grid Pathfinding 5000x5000

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		threads							
weight		1	2	3	4	5	6	7	8
wPBNF	1.1	0.84	1.51	2.23	2.87	3.41	4.02	4.55	5.03
	1.2	0.77	1.42	2.09	2.69	3.24	3.72	4.12	4.52
	1.4	0.42	0.92	1.39	1.83	2.31	2.51	2.77	2.98
	1.8	0.62	0.72	0.81	0.82	0.83	0.86	0.85	0.87
	3.4	0.71	0.69	0.69	0.69	0.67	0.65	0.64	0.64
wAHDA*	1.1	0.87	1.41	2.04	1.82	2.74	3.40	4.09	3.57
	1.2	0.79	1.22	1.82	1.75	3.28	3.29	3.96	3.48
	1.4	0.31	0.69	1.51	1.55	2.62	2.47	3.05	2.68
	1.8	0.55	0.74	0.94	0.69	0.83	0.81	0.74	0.64
	3.4	0.71	0.69	0.73	0.51	0.59	0.59	0.56	0.48

Speedup over serial wA

- wPBNF gave the best performance at all but 1 thread.
- Lower weight gives more speedup.

Korf's 100 15-Puzzles

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		threads							
weight		1	2	3	4	5	6	7	8
wPBNF	1.4	0.86	1.40	2.27	2.01	2.41	2.48	2.68	2.58
	1.7	0.98	1.34	1.70	1.87	2.33	2.63	2.33	2.08
	2.0	0.96	1.17	1.45	1.44	1.57	1.48	1.56	1.48
	3.0	1.09	1.34	1.46	1.44	1.41	1.34	1.38	1.21
	5.0	0.93	1.04	1.12	1.04	1.07	1.13	0.99	0.92
wAHDA*	1.4	0.84	1.50	1.90	2.33	2.37	2.39	2.39	2.47
	1.7	0.82	1.42	1.66	1.90	1.68	1.75	1.64	1.70
	2.0	0.80	1.52	1.48	1.74	1.44	1.23	1.25	1.23
	3.0	0.75	1.39	1.30	1.31	1.10	0.88	0.73	0.70
	5.0	0.71	1.11	0.91	0.85	0.70	0.54	0.45	0.43

Speedup over serial wA

- wPBNF often gave the best performance.
- Lower weight gives more speedup.

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		wAPRA*				wAHDA*				wPBNF			
		1.5	2	3	5	1.5	2	3	5	1.5	2	3	5
2 threads	logistics-8	0.99	1.02	0.59	1.37	1.25	1.11	0.80	1.51	2.68	2.27	4.06	1.00
	blocks-16	1.29	0.88	4.12	0.30	1.52	1.09	4.86	0.38	0.93	0.54	0.48	1.32
	gripper-7	0.76	0.76	0.77	0.77	1.36	1.35	1.33	1.30	2.01	1.99	1.99	2.02
	satellite-6	0.68	0.93	0.70	0.75	1.15	1.09	1.28	1.44	2.02	1.53	5.90	3.04
	elevator-12	0.65	0.72	0.71	0.77	1.16	1.20	1.27	1.22	2.02	2.08	2.21	2.15
	freecell-3	1.03	1.00	1.78	1.61	1.49	1.20	7.56	1.40	2.06	0.84	8.11	10.69
	depots-13	0.73	1.25	0.97	1.08	0.92	1.29	0.96	1.09	2.70	4.49	0.82	0.81
	driverlog-11	0.91	0.79	0.94	0.93	1.30	0.97	0.96	0.93	0.85	0.19	0.69	0.62
	gripper-8	0.63	0.61	0.62	0.62	1.14	1.16	1.15	1.16	2.06	2.04	2.08	2.07
7 threads	logistics-8	3.19	3.10	3.26	2.58	4.59	4.60	3.61	2.58	7.10	6.88	1.91	0.46
	blocks-16	3.04	1.37	1.08	0.37	3.60	1.62	0.56	0.32	2.87	0.70	0.37	1.26
	gripper-7	1.71	1.74	1.73	1.82	3.71	3.66	3.74	3.83	5.67	5.09	5.07	5.18
	satellite-6	1.11	1.01	1.29	1.44	3.22	3.57	3.05	3.60	4.42	2.85	2.68	5.89
	elevator-12	0.94	0.97	1.04	1.02	2.77	2.88	2.98	3.03	6.32	6.31	6.60	7.10
	freecell-3	3.09	7.99	2.67	2.93	4.77	2.71	48.66	4.77	7.01	2.31	131.12	1,721.33
	depots-13	2.38	5.36	1.13	1.17	2.98	6.09	1.22	1.17	3.12	1.80	0.87	0.88
	driverlog-11	1.90	1.25	0.93	0.92	3.52	1.48	0.95	0.92	1.72	0.43	0.67	0.42
	gripper-8	1.70	1.68	1.68	1.74	3.71	3.63	3.67	4.00	5.85	5.31	5.40	5.44

Speedup over serial wA*

- Most red is under wPBNF (13 of 18).
- Blue is everywhere.

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- In general speedup was not as good as optimal search.
 - ◆ Some harder problems gave excellent speedup.
- Lower weights can increase benefit of parallelizing.

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- Simple to convert PRA* and PBNF to anytime.
 - ◆ Sort open lists on $f'(n) = g(n) + w \cdot h(n)$.
 - ◆ Stop when $\min_{n \in open} f(n) \geq g(s)$ (same as optimal).
- Anytime PBNF
 - ◆ Sort n block free-list on $\min_{n \in open} f'(n)$.
- Parallel analogue to Anytime Weighted A* (Hansen and Zhou, JAIR 2007)

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		AwAPRA*				AwAHDA*				AwPBNF			
		1.5	2	3	5	1.5	2	3	5	1.5	2	3	5
2 threads	logistics-6	1.09	1.06	1.40	1.40	1.23	1.21	1.59	1.66	1.06	1.35	1.94	1.98
	blocks-14	1.36	7.76	56.41	90.16	1.62	9.90	63.60	110.16	1.91	1.99	13.22	22.36
	gripper-7	0.78	0.77	0.76	0.75	1.35	1.33	1.32	1.33	2.05	1.96	1.99	1.95
	satellite-6	0.77	0.78	0.78	0.76	1.26	1.23	1.24	1.23	1.58	1.96	1.98	1.91
	elevator-12	0.64	0.67	0.69	0.70	1.20	1.19	1.16	1.17	2.01	2.07	2.13	2.07
	freecell-3	1.37	1.43	4.61	1.37	1.66	1.68	5.65	1.95	1.93	1.06	2.78	6.23
	depots-7	1.24	1.30	1.30	2.68	1.51	1.51	1.50	3.18	1.94	2.00	2.01	4.10
	driverlog-11	1.15	1.19	1.11	1.20	1.50	1.55	1.46	1.54	1.95	2.10	1.99	0.77
7 threads	gripper-8	0.61	0.62	0.62	0.62	1.16	1.11	1.14	1.11	2.04	2.05	2.09	2.06
	logistics-6	1.45	1.43	1.81	1.81	2.87	2.81	3.65	3.74	2.04	2.46	4.19	4.21
	blocks-14	2.54	15.63	98.52	177.08	3.30	19.91	132.97	231.45	3.72	22.37	25.69	7.20
	gripper-7	1.77	1.68	1.71	1.73	3.75	3.69	3.61	3.67	5.61	5.05	5.03	5.06
	satellite-6	1.22	1.22	1.26	1.26	3.56	3.46	3.51	3.50	5.96	4.66	5.74	4.70
	elevator-12	0.93	0.93	0.95	0.94	2.77	2.75	2.79	2.77	6.18	6.03	6.20	6.05
	freecell-3	3.64	3.75	11.59	4.44	5.00	4.97	16.36	21.57	3.54	1.50	15.32	11.46
	depots-7	3.60	3.64	3.65	7.60	4.41	4.42	4.40	9.25	5.74	5.52	5.48	10.84
driverlog-11	3.04	3.20	3.05	3.17	4.74	4.82	4.66	4.87	5.78	5.83	5.73	2.18	
gripper-8	1.72	1.67	1.70	1.69	3.65	3.61	3.66	3.66	5.82	5.36	5.39	5.39	

Speedup over serial AwA* (to convergence)

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- Outperforms serial anytime search.
- AwPBNF gave the best performance on all but three domains.
- AwAHDA* occasionally gave much better performance.

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- Parallel search can make your programs run faster today.
 - ◆ Multi-core is not going away.
 - ◆ Email me for the code (C++): burns.ethan@gmail.com
- PBNF and PRA* are simple and general.
 - ◆ Easily extendable to weighted and anytime search.
 - ◆ PBNF generally performed better than the other algorithms tested.
- Abstraction is beneficial for parallel search.
- Parallel search is more beneficial on harder problems.

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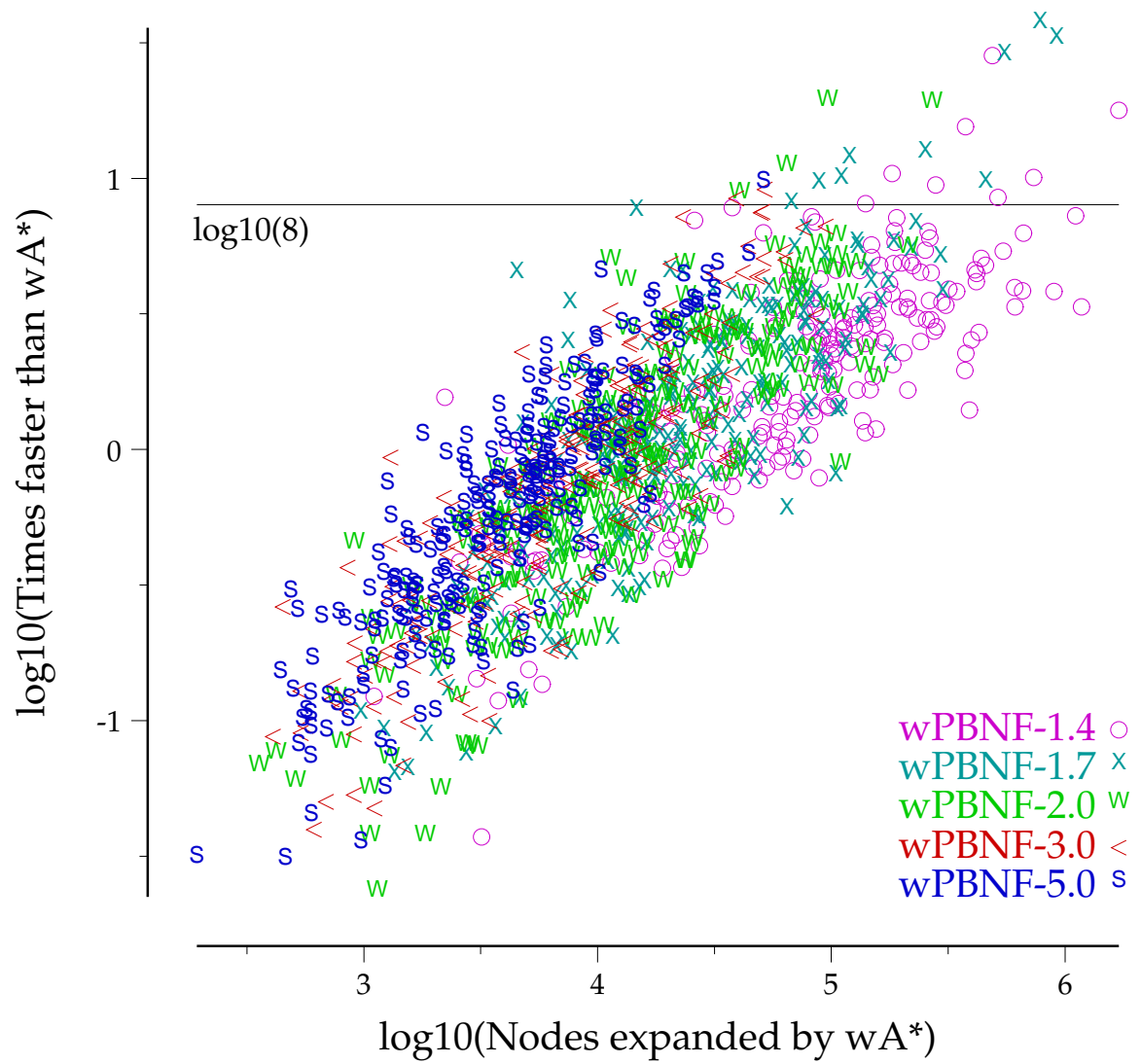
- Problem Difficulty
- Hull Plots
- Grid Pathfinding
- Sliding Tiles
- New: Pruning

Additional Slides

Difficulty versus Advantage over wA*

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- PRA*
- PBNF
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Sliding Tiles wPBNF v.s. wA*



Hull Plots

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PBNF

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Suboptimal Search

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■ Problem Difficulty

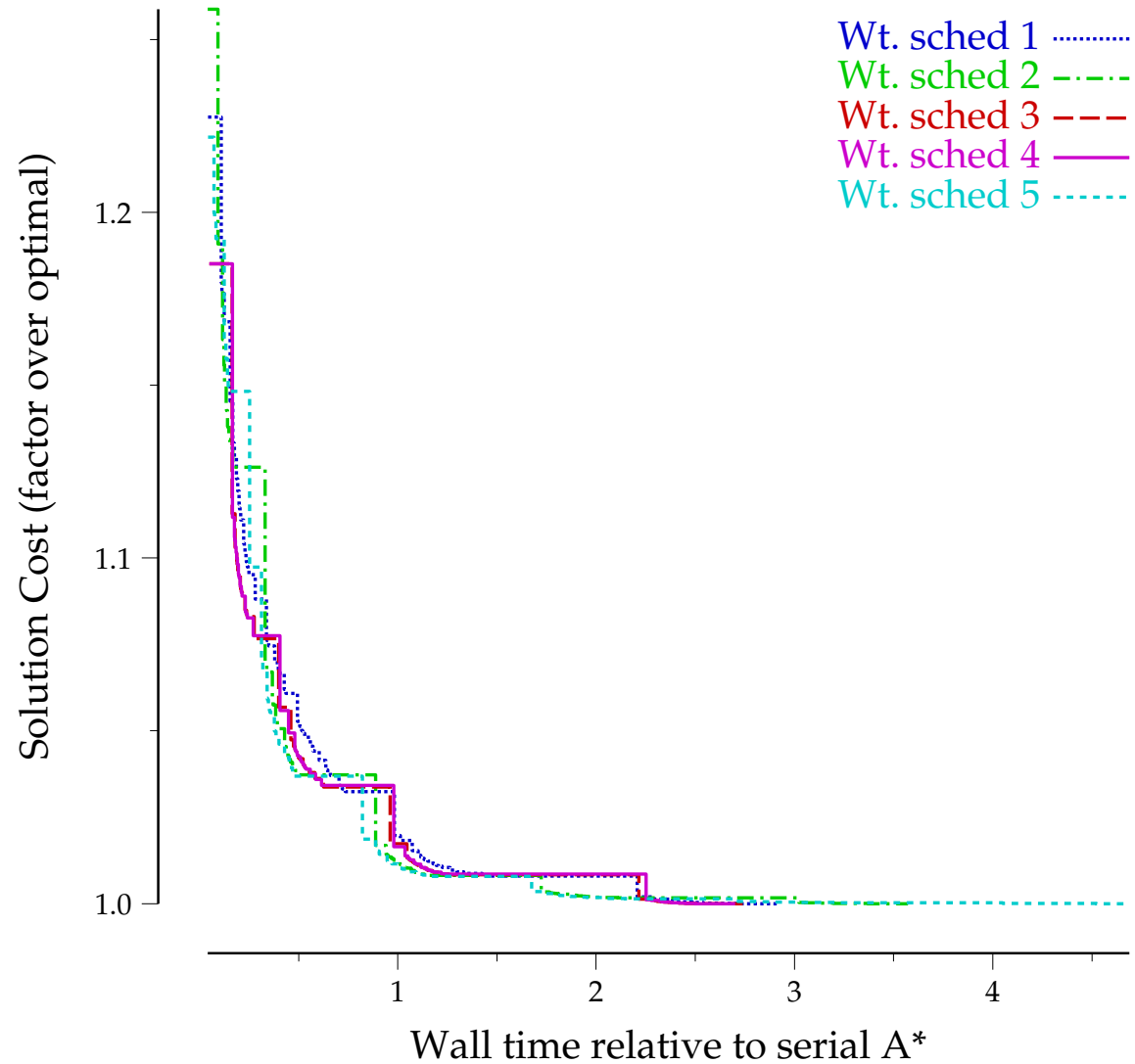
■ Hull Plots

■ Grid Pathfinding

■ Sliding Tiles

■ New: Pruning

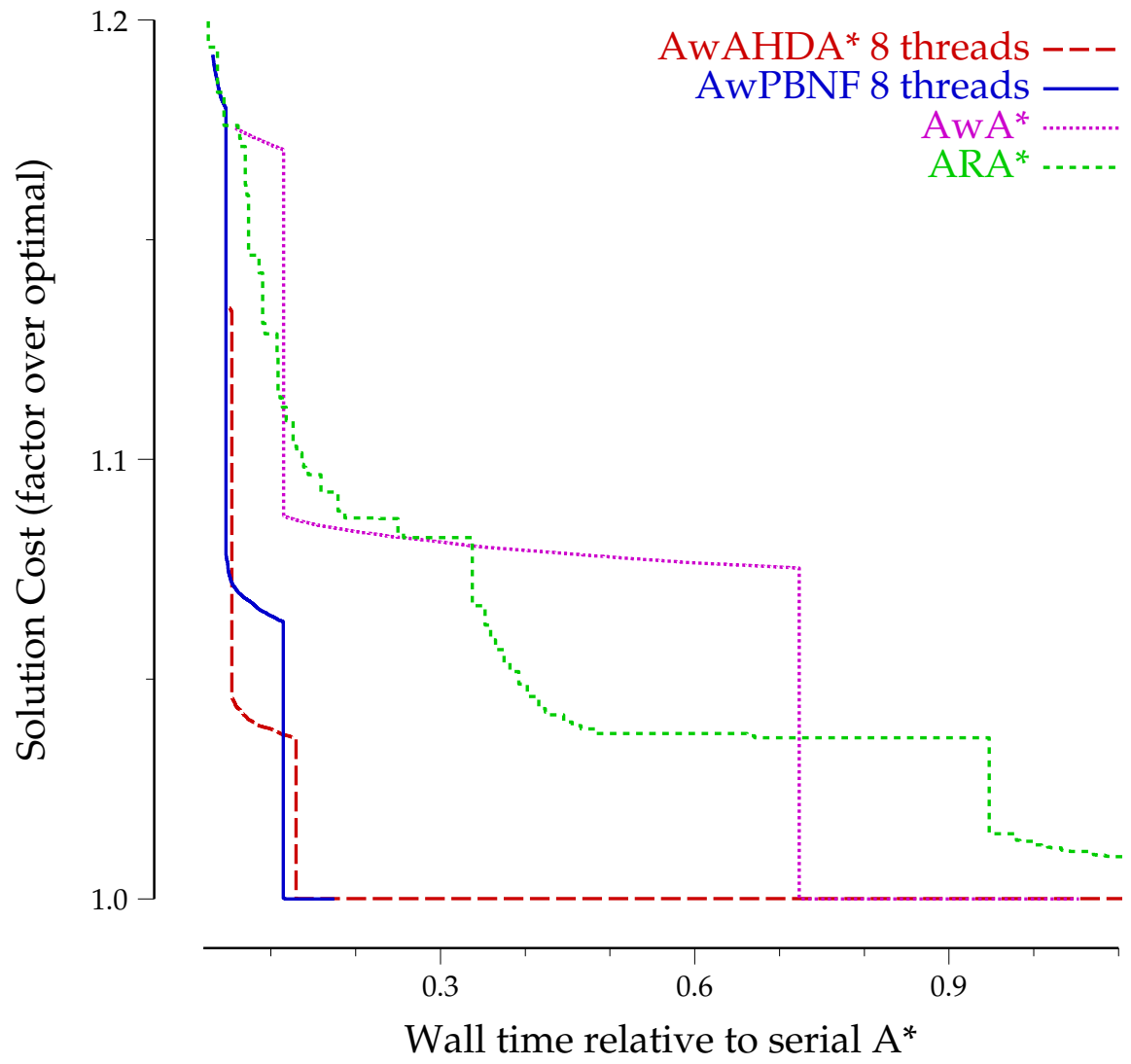
Raw Data for ARA*



Four-way Grid Pathfinding 5000x5000

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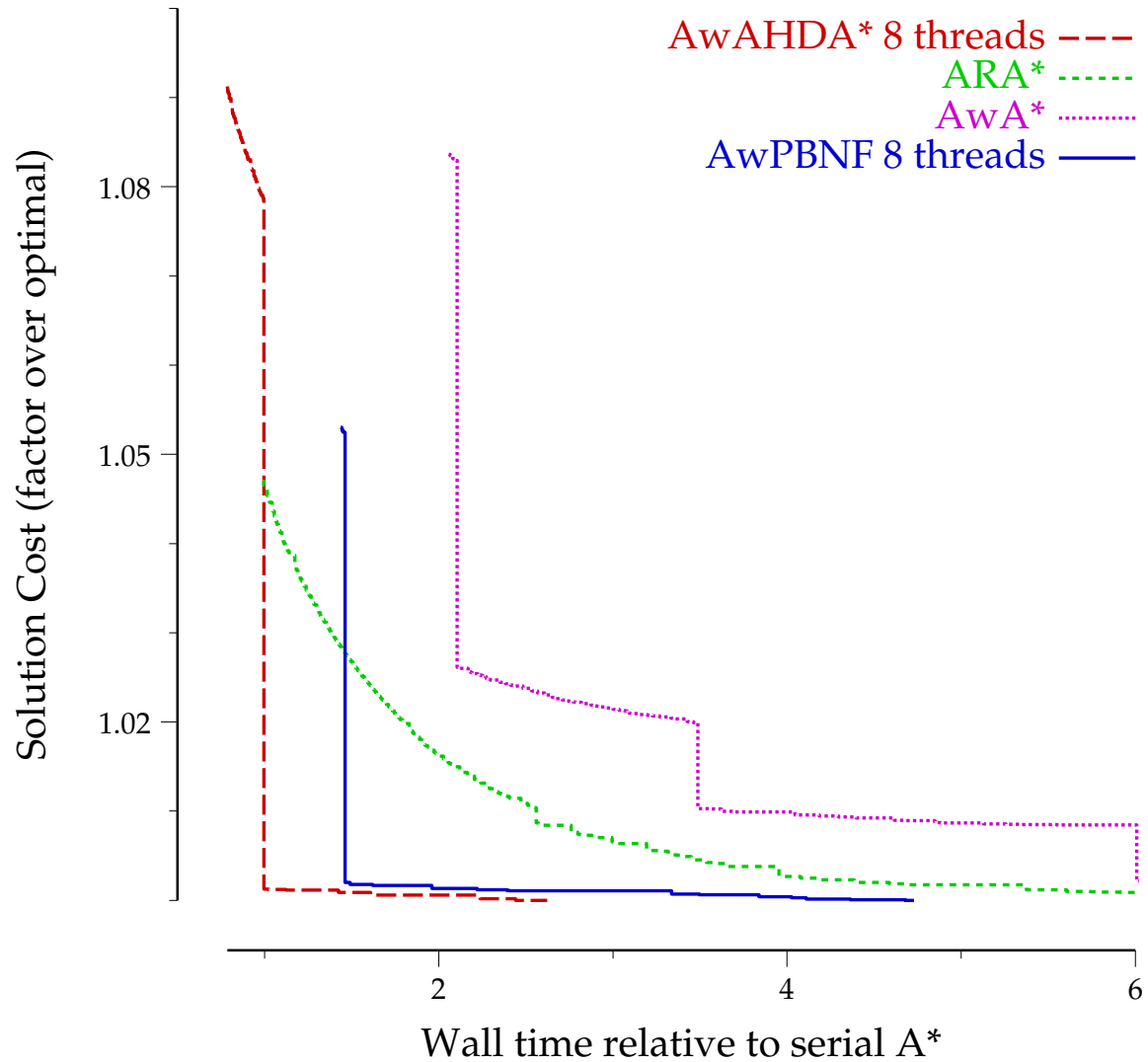
Grid Unit Four-way 5000x5000



Easy 15-Puzzles

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15 puzzles: 250 random easy instances



Pruning poor nodes

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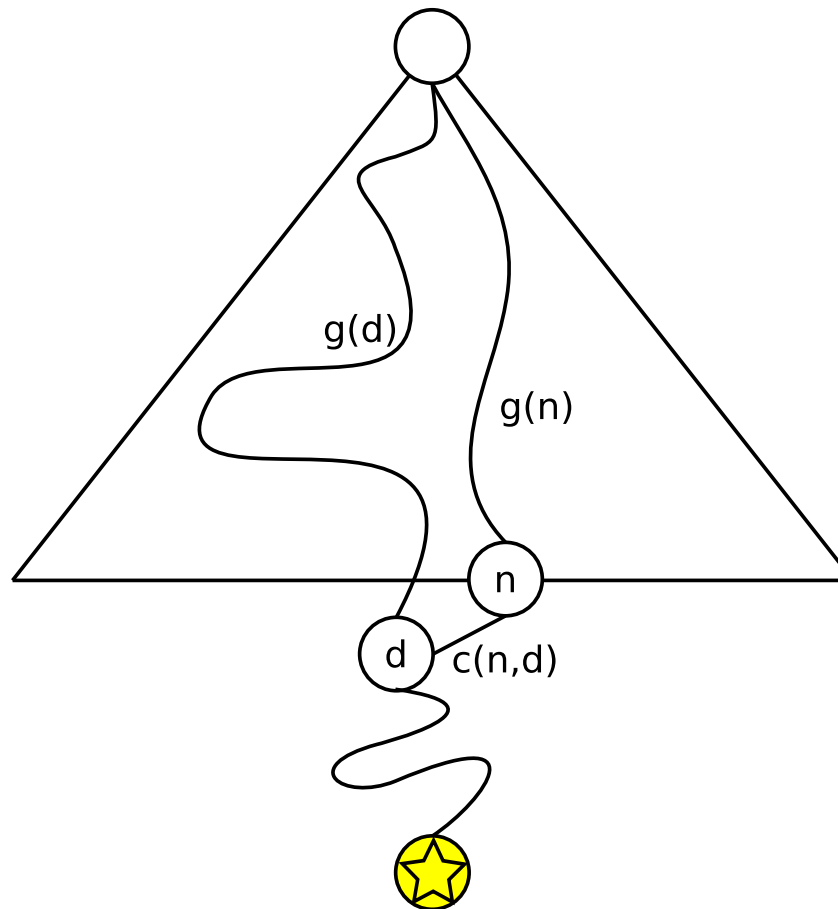
■ Sliding Tiles

■ **New: Pruning**

Theorem: Can prune a node n if $w \cdot f(n) \geq g(s)$, where s is the incumbent solution and w is the desired bound.

Pruning duplicate nodes

Theorem: No need to re-expand d if the old $g(d) \leq g(n) + w \cdot c^*(n, d)$, where $c^*(n, d)$ is the cost of the path from n to d .



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